



*Connecting a QJ71MT91
Modbus/TCP Module to a
Mitsubishi VFD*

Silhouettes of three runners in motion, positioned to the left of the word "Quick".

Quick

Start Guide

A graphic of a "START" button with a mouse cursor pointing at it, located to the right of the word "Quick".

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FURTHER READING REFERENCE LIST

QJ71MT91, GX Configurator-MB MODBUS(R)_TCP Interface Module User's Manual SH_NA_080446ENG-G

FR-A700 Instruction Manual (Applied), NA Version IB_NA_0600255ENG-E

FR-A7N-ETH User's Manual V2.320 (www.iccdesigns.com or <http://www.iccdesigns.com/fr-a7n-eth.html>)

ATTACHMENTS

QJ71MT91 Demo.gwx - GX Works2 File (Using the Module as a Master to a Slave Device(s))

QJ71MT91 Modbus Slave.gwx - GX Works2 File (Using the Module as a Slave from a Master Device)

QJ71MT91 as a Slave Addendum Manual.pdf – Addendum Manual for SLAVE Setup Only

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Chapter 1 Introduction

This Quick Start Guide (QSG) provides instructions on how to set a QJ71MT91 (MT91) Modbus/TCP Communications Module to communicate to a Mitsubishi A700, F700 or E700 Series Variable Frequency Drive (VFD) using the Automatic Communication Parameters in the Intelligent Function Module Utility in GX Works2 Programmable Logic Controller (PLC) Software. **Installed in the VFD is a FR-A7N-ETH Option Module.**

The MT91 Master module supports up to 64 Remote Connections. A Slave Device can use One (1) or multiple Connections depending upon the setup.

The objective of this QSG is to assist the users to quickly setup the iQ or Q PLC CPU program to have the MT91 Module to send commands to the VFD and receive status information and data from the VFD. This QSG contains the necessary configuration information for the iQ or Q PLC and the 700 Series VFD.

If the MT91 Module is to be used as a SLAVE (Server) from a Modbus/TCP MASTER (Client) please reference the QJ71MT91 as a Slave Addendum Manual and GXW2 Modbus Slave program.

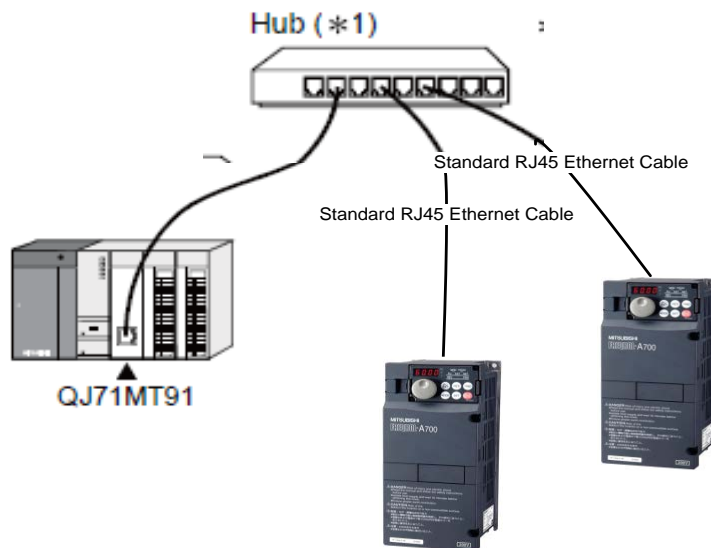


Figure 1 QJ71MT91 Module Ethernet Connection to a A700, F700 or E700 VFDs

Chapter 2 System Overview

This QSG was setup using the following test system. The PLC Programming software is GX Works2 V1.73B or Greater. Melsoft Navigator was NOT used or required.

The FR-A7N-ETH module is the Server and the PLC CPU is the Client.

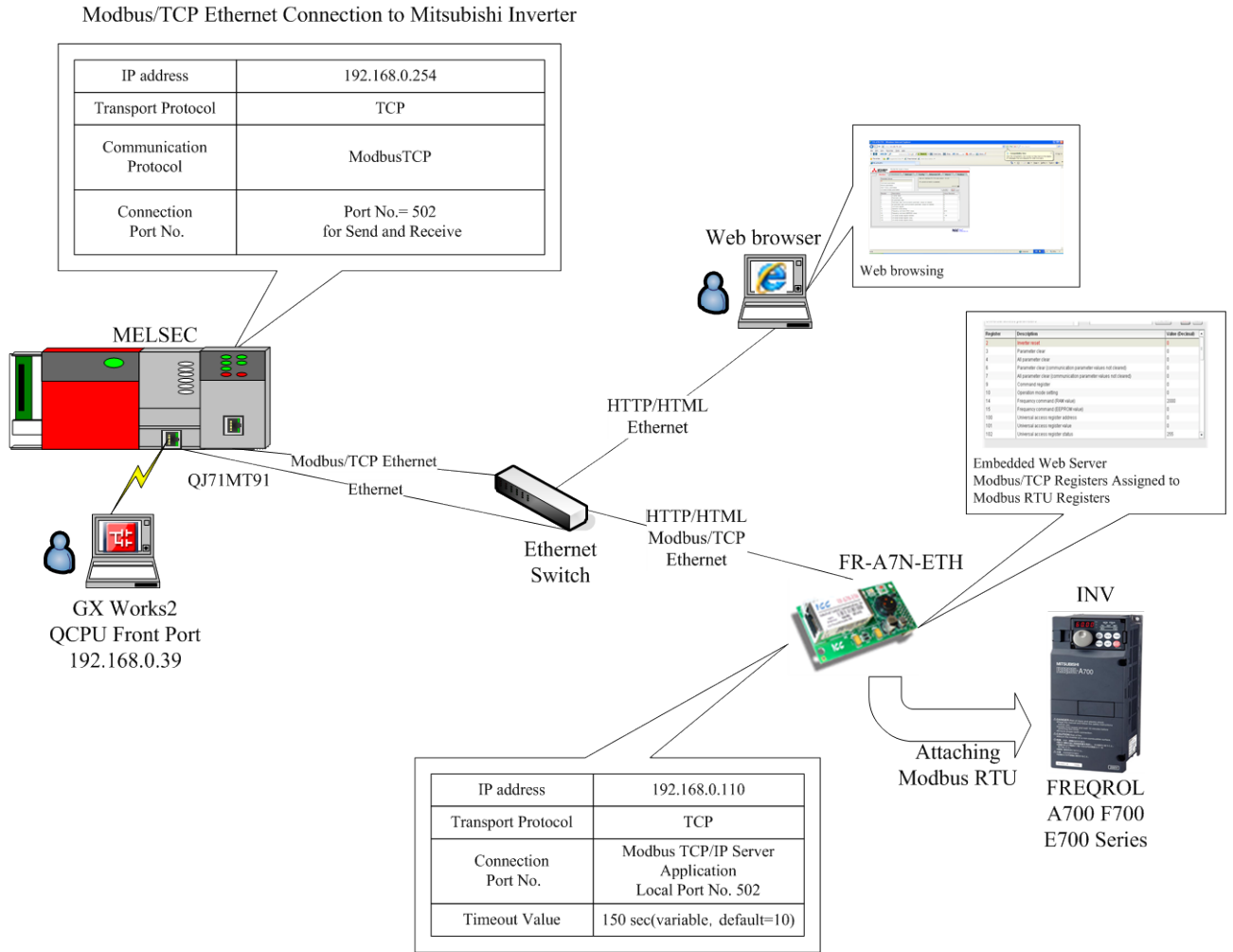


Figure 2.1 Architecture of Test System

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Chapter 3 VFD Parameter Setup and Wiring

3.1 E700 Connecting the FR-A7N-ETH to the Standard RJ45 Parameter Unit (PU) Port

<u>Parameter</u>	<u>Description</u>	<u>Setting</u>
117	PU Station #	1
118	PU Comms Speed	384
120	PU Parity	2 (Default)
122	PU Comms Timeout	9999
340	Network Mode	10
549	Protocol Selection	1 (Modbus Protocol)
77	Parameter Write Mode	2

Use the OPTIONAL cable with the FR-A7N-ETH module to connect to the RJ45 Port built into the VFD as shown below and in the FR-A7N-ETH manual. Remember to cycle power to the VFD after setting any communication related parameter.



Figure 3.1 E700-NET-CBL Option Cable

3.2 A700/F700 Connecting the FR-A7N-ETH to the RS-485 Terminal Blocks

Parameter	Description	Setting
331	RS-485 Station #	1
332	RS-485 Speed	384 (38.4K)
334	RS-485 Parity	2 (Default)
340	Network Mode	10
549	Protocol Selection	1 (Modbus Protocol)
77	Parameter Write Mode	2

Use the supplied cable that comes with the FR-A7N-ETH module to connect to the RS-485 Terminals built into the VFD as shown below and in the FR-A7N-ETH manual. Remember to cycle power to the VFD after setting any communication related parameter.

Communication operation and setting

4.19.2 Wiring and arrangement of RS-485 terminals

(1) RS-485 terminal layout

Terminating resistor switch
Factory-set to "OPEN".
Set only the terminating resistor switch of the remotest inverter to the "100Ω" position.

Name	Description
RDA1 (RXD1+)	Inverter receive+
RDB1 (RXD1-)	Inverter receive-
RDA2 (RXD2+)	Inverter receive+ (for branch)
RDB2 (RXD2-)	Inverter receive- (for branch)
SDA1 (TXD1+)	Inverter send+
SDB1 (TXD1-)	Inverter send-
SDA2 (TXD2+)	Inverter send+ (for branch)
SDB2 (TXD2-)	Inverter send- (for branch)
P5S (VCC)	5V Permissible load current 100mA
SG (GND)	Ground (connected to terminal SD)

(2) Connection of RS-485 terminals and wires

Loosen the terminal screw and insert the cable into the terminal.

Screw size	M2	Wire the stripped cable after twisting it to prevent it from becoming loose. In addition, do not solder it. Use a blade terminal as necessary.
Tightening torque	0.22N·m to 0.25N·m	
Cable size	0.3mm ² to 0.75mm ²	
Screwdriver	Small \ominus flathead screwdriver (Tip thickness: 0.4mm /tip width: 2.5mm)	

Figure 3.2.1 Terminal Block Layout

3.3 FR-A7N-ETH Module Setup

3.3.1. IP Address Settings

Use the ICC Finder software that came with the product or that can be downloaded at <http://www.iccdesigns.com/downloads/software/icc-finder.html> . It will automatically find the Module if connected to the network. If the IP address needs to be changed, select “Configure IP Settings”. Once the IP Address has been changed make sure your computer is on the same subnet as the module and select: “Open Web Interface”. Username is “root” and password is “icc”.

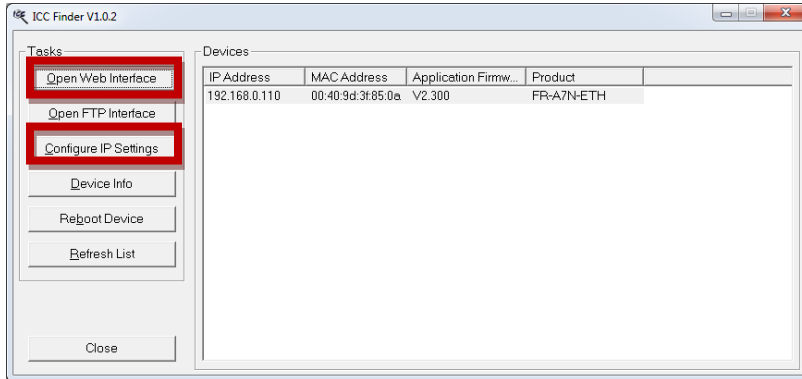


Figure 3.3.1.1 ICC Finder Software

Once the Web Interface is open, select the Config Tab and enter IP Address information if needed.

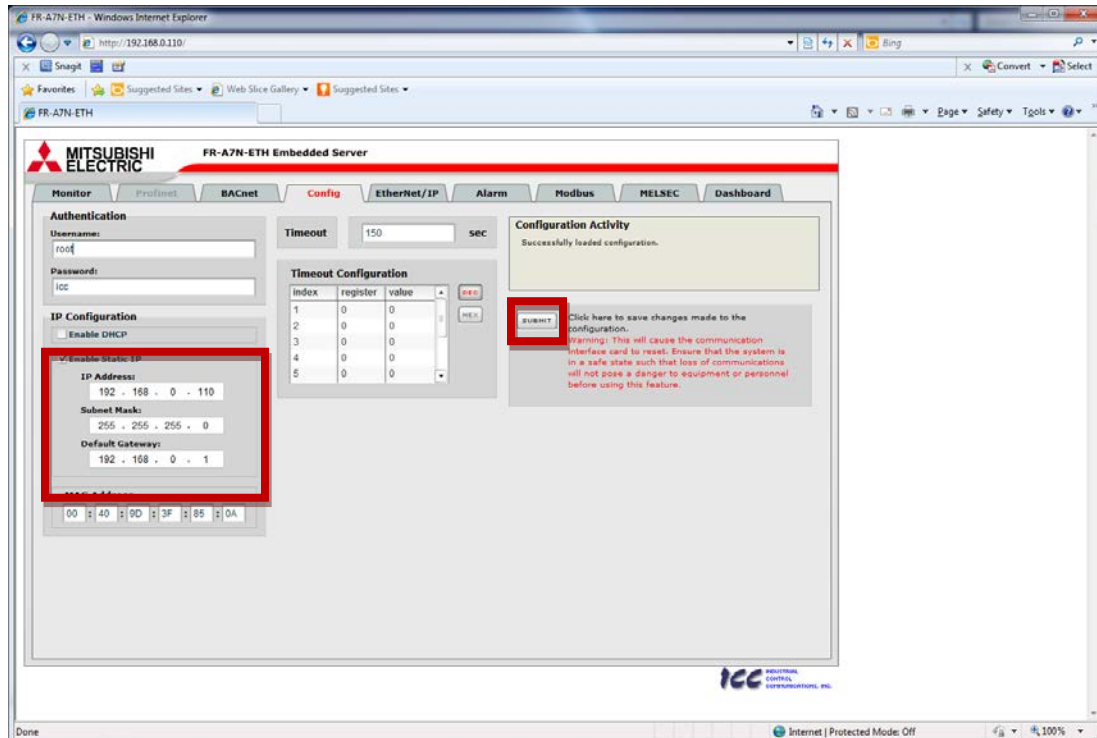


Figure 3.3.1.2 Web Interface Config Tab

Select **SUBMIT** to make changes in the module.

3.3.2. Modbus to Modbus/TCP Address Mapping

Select the Modbus Tab.

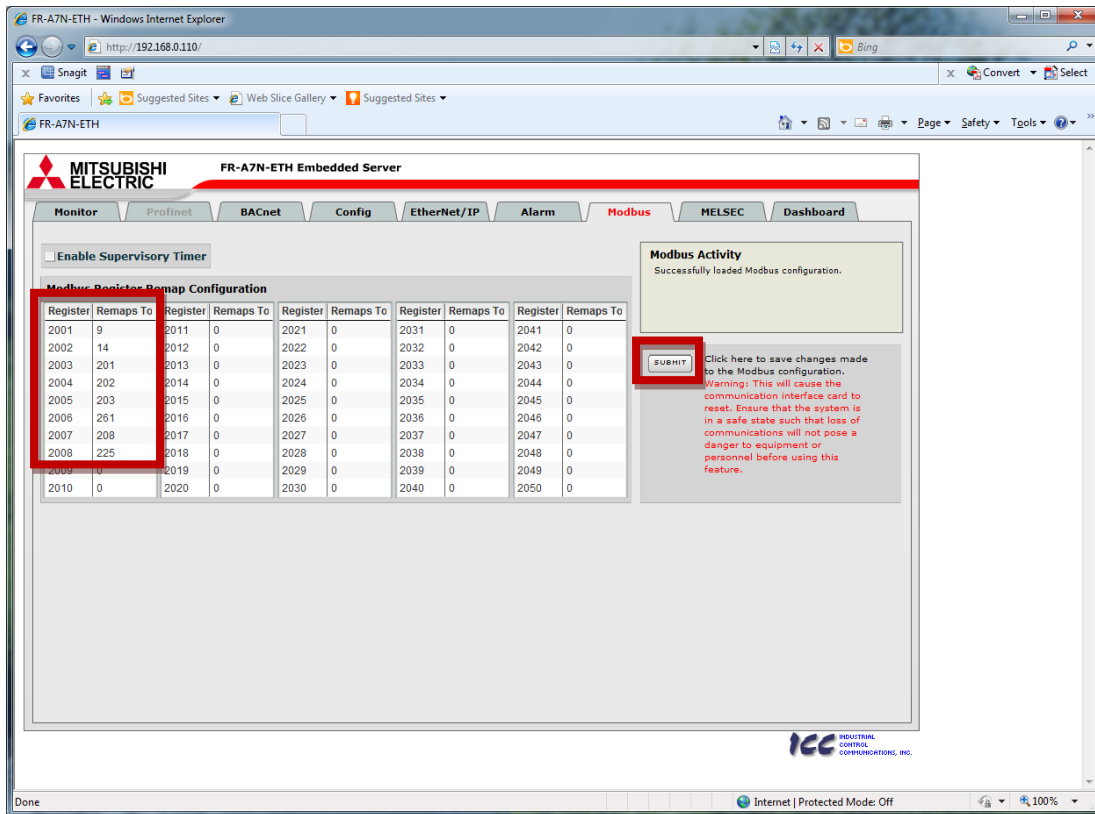


Figure 3.3.2 Modbus Address Remapping Tab

The Register Column is the Modbus/TCP register starting at 40xxxx.

The Remaps to Column is the Modbus register this is being used by the VFD.

Choose the following for the Remapping

Modbus/TCP Modbus

1. 2001 = 9 = 40009 = VFD Command Bits Write Word
2. 2002 = 14 = 40014 = VFD Frequency Write Word
3. 2003= 201 = 40201 = VFD Current Frequency
4. 2004 = 202 = 40202 = VFD Current Current
5. 2005 = 203 = 40203 = VFD Current Voltage
6. 2006 = 261 = 40261 = VFD Current Status Bits Word
7. 2007 = 208 = 40208 = VFD Current DC Bus Voltage
8. 2008 = 225 = 40225 = VFD Cumulative Power (1kWh)

Select **SUBMIT** to make changes in the module.

3.3.3. Monitoring

Select the Monitor Tab.

The screenshot shows the web interface for the Mitsubishi Electric FR-A7N-ETH Embedded Server. The 'Monitor' tab is selected, displaying a table of parameters and registers. The table has four columns: Parameter, Register, Description, and Value (Decimal). The values are as follows:

Parameter	Register	Description	Value (Decimal)
	2	Inverter reset	0
	3	Parameter clear	0
	4	All parameter clear	0
	6	Parameter clear (communication parameter values not cleared)	0
	7	All parameter clear (communication parameter values not cleared)	0
	9	Command register	2
	10	Operation mode setting	0
	14	Frequency command (RAM value)	1000
	15	Frequency command (EEPROM value)	0
	100	Universal access register address	0
	101	Universal access register value	0
	102	Universal access register status	255
	201	Output frequency	1000
	202	Output current	127
	203	Output voltage	425
	205	Frequency setting	1000
	206	Running speed (A700 & F700 only)	300
	207	Motor torque (A700 & E700 only)	0

Additional information visible in the interface includes: CPU firmware version: V2.300, XML socket connection succeeded, and the ICC logo (Industrial Control Communications, Inc.).

Figure 3.3.3 Monitor Tab

From the Monitor Tab you can see the values being written to or read from the Modbus addresses for the VFD. If the Modbus address is not mapped to a Modbus/TCP address it can be forced from this tab if needed. This is an excellent way to test communication from your MT91 Master and the Module/VFD.

Chapter 4 Modbus/TCP Protocol

4.1 Automatic Communication Function

This QSG uses the Automatic Communication Function of Modbus/TCP Communication

(1) Supporting master function of MODBUS® /TCP communication

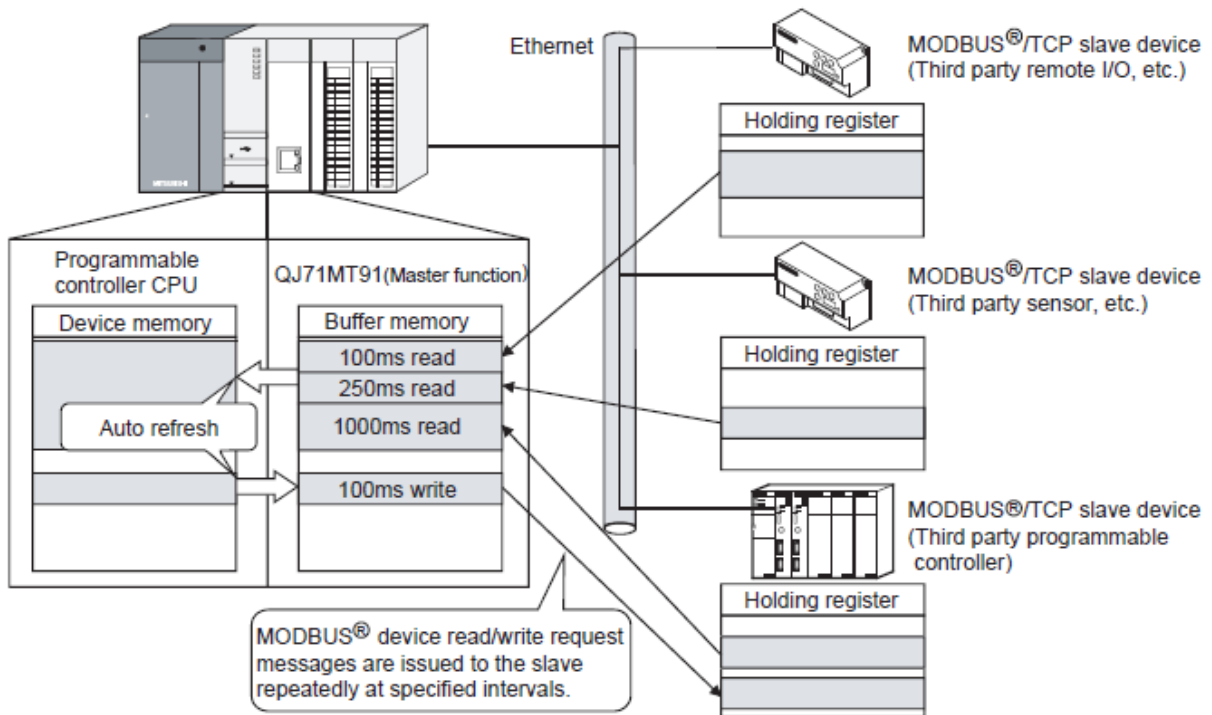
The QJ71MT91 supports the master function of MODBUS® /TCP communication, which is an open network system for factory automation, and it is compatible with various MODBUS® /TCP slave devices (hereafter abbreviated to the slaves) of other manufactures.

The master function supports the following two functions.

(a) Automatic communication function

By setting the automatic communication parameters, MODBUS® device data can be automatically read from or written to the slaves at the specified intervals using the QJ71MT91 buffer memory. (*1)

Data can be transferred between the QJ71MT91 buffer memory and programmable controller CPU device memory by making the auto refresh setting with the utility package (GX Configurator-MB) or accessing a intelligent function module device with a sequence program.



*1: The MODBUS® device indicates the device area of the slave where data can be read/written in response to a request from the master.

Figure 4.1 Modbus/TCP Protocol – Automatic Communication Function

The Buffer Memory Locations (BFMs) that the Automatic Communication Function uses are shown below. For data Read from the Slave a BFM of 1000h to 1FFFh and data Written to a Slave a BFM of 3000h to 3FFFh have to be defined in the Automatic Communication Parameters for each Read or Write. See Section 5.2 for **Head Buffer Memory Address** Parameter Setup.

(4) Automatic communication function buffer areas

(a) Automatic communication function buffer areas

The automatic communication function uses the following buffer memory areas.

Name	Application	Buffer Memory Address
Automatic communication function buffer input area	Stores data read from the slave	1000 _H to 1FFF _H
Automatic communication function buffer output area	Stores data to be written to the slave	3000 _H to 3FFF _H

Figure 4.1.2 Automatic Communication Function Buffer Memory Locations

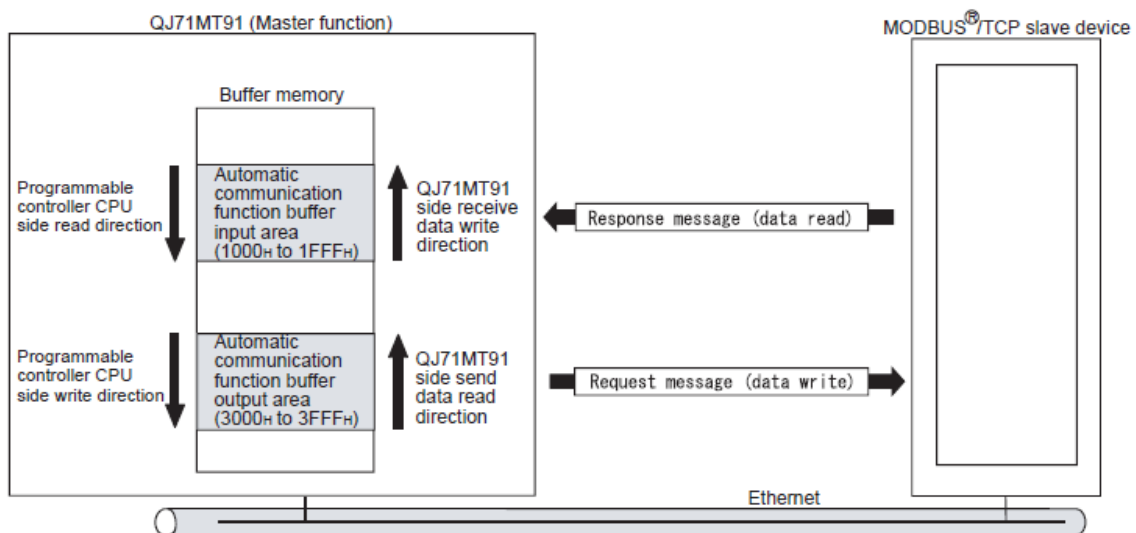


Figure 4.1.3 Automatic Communication Function Buffer Memory Transfer Directions

4.2 Modbus Performance Specifications

The following shows the Modbus performance specification.

This section provides the performance specifications of the QJ71MT91.

Item		Specifications		Reference Section	
		10BASE-T	100BASE-TX		
Transmission specifications	Data transmission rate	10Mbps	100Mbps	—	
	Transmission method	Base band			
	Maximum node-to-node distance	200m (656.16ft.)			
	Maximum segment length * 1	100m (328.08ft.)			
	Number of cascade connection stages	Max. 4 stages	Max. 2 stages		
	Maximum number of connections * 2	64 connections			
	Number of routers that can be set	1 default router + any 8 routers			
	Cable	Cable compliant with the IEEE802.3 10BASE-T Standard (unshielded twisted pair cable (UTP cable), Category 3 (4, 5))	Cable compliant with the IEEE802.3 100BASE-TX Standard (shielded twisted pair cable (STP cable), Category 5)	Section 2.2	
Connector applicable for external wiring		RJ45		—	
Master function	Automatic communication function	Number of slaves * 3	64 slaves	—	
		Function (for send)	7 functions	Chapter 4	
		Input area size	4k words	Section 3.3.1	
		Output area size	4k words	—	
	Dedicated instruction	Number of instructions that can be executed concurrently * 4	Up to 8 instructions		—
		Function (for send)	MBRW instruction: 9 functions MBREQ instruction: 19 functions	Chapter 4	
Input area size		Max. 253 bytes per instruction	Chapter 4		
Output area size	Max. 253 bytes per instruction	—			
Slave function	Automatic response function	Function (for receive)	12 functions	Chapter 4	
	MODBUS [®] device size	Coil	64k points	Section 7.4.1	
		Input	64k points		
		Input register	64k points		
		Holding register	64k points		
Extended file register	Max. 4086k points	—			
No. of simultaneously acceptable request messages	64		—		
GX Developer connection function	Number of simultaneously connectable GX Developers	Max. 8 GX Developers		Section 7.2.3	
Number of occupied I/O points		32 points		—	
5VDC internal current consumption		0.52A		—	
External dimensions		98 (3.86 in.) (H) × 27.4 (1.08 in.) (W) × 90 (3.54 in.) (D) [mm]		Appendix 1	
Weight		0.11kg		—	

* 1: Length between a hub and a node.

* 2: Indicates the number of TCP connections that can be established simultaneously.

* 3: Indicates the maximum number of slaves that can be communication targets.

* 4: Indicates the maximum number of dedicated instructions that can be started simultaneously from a sequence program.

Figure 4.2.1 Performance Specs

4.3 I/O Signal List

The follow I/O points are used for the MT91 module. These points are for a module in slot 0 of the rack. The module takes up 32 Digital Inputs and 32 Digital Outputs. I/O boxed in RED is used in the Demo Program for enabling Modbus/TCP Communications.

Signal Direction QJ71MT91 → Programmable controller CPU			Signal Direction Programmable controller CPU → QJ71MT91		
Device No.	Signal name	Reference section	Device No.	Signal name	Reference section
X0	Module READY *1 ON : Accessible OFF: Inaccessible	Section 11.1	Y0	Use prohibited	—
X1	Basic parameter setting, normally completed ON : Normally completed OFF: —	Section 9.1.1	Y1	Basic parameter setting request ON : Being requested OFF: Not requested	Section 9.1.1
X2	Basic parameter setting, error completed ON : Error completed OFF: —		Y2	Use prohibited	—
X3	Basic parameter setting existence ON : Parameters set OFF: No parameters set		Y3		—
X4	Automatic communication parameter setting, normally completed ON : Normally completed OFF: —	Section 5.2.1, 9.1.2	Y4	Automatic communication parameter setting request/automatic communication start request ON : Parameter setting being requested/start being requested OFF: No parameter setting requested/no start requested	Section 5.2.1, 9.1.2
X5	Automatic communication parameter setting, error completed ON : Error completed OFF: —		Y5	Use prohibited	—
X6	Automatic communication operation status ON : Operating OFF: Stopped	Section 5.2.1	Y6	Automatic communication stop request ON : Being requested OFF: Not requested	Section 5.2.1
X7	Automatic communication error status ON : Error occurred OFF: No error		Y7	Use prohibited	—
X8	MODBUS® device assignment parameter setting, normally completed ON : Normally completed OFF: —	Section 9.1.3	Y8	MODBUS® device assignment parameter setting request ON : Being requested OFF: Not requested	Section 9.1.3
X9	MODBUS® device assignment parameter setting, error completed ON : Error completed OFF: —		Y9	Use prohibited	—

*1: Turns ON when the QJ71MT91 is ready after the programmable controller is turned ON from OFF or after the programmable controller CPU is reset.

Figure 4.3.1 I/O Signal List 1

Signal Direction QJ71MT91 → Programmable controller CPU			Signal Direction Programmable controller CPU → QJ71MT91		
Device No.	Signal name	Reference section	Device No.	Signal name	Reference section
XA	MODBUS® device assignment parameter setting existence ON : Parameters set OFF: No parameters set	Section 9.1.3	YA		—
XB	Use prohibited	—	YB	Use prohibited	—
XC		—	YC		—
XD		—	YD		—
XE		—	YE		—
XF		—	YF		—
X10		—	Y10		—
X11		—	Y11		—
X12		—	Y12		—
X13		—	Y13		—
X14		—	Y14		—
X15		—	Y15		—
X16		—	Y16		—
X17		—	Y17		—
X18		—	Y18		—
X19	—	Y19	—		
X1A	—	Y1A	—		
X1B	COM.ERR.LED status ON : Lit OFF: Not lit	Section 11.4.2	Y1B	COM. ERR. LED OFF request ON : Being requested OFF: Not requested	Section 11.4.2
X1C	PING test completed ON : PING test completed OFF: —	Section 11.5.2	Y1C	PING test execution request ON : PING test execution being requested OFF: PING test execution not request	Section 11.5.2
X1D	Use prohibited	—	Y1D	Use prohibited	—
X1E		—	Y1E		—
X1F	Watch dog timer error ON : Module error occurred OFF: Module operating normally	Section 11.1	Y1F		—

Figure 4.3.2 I/O Signal List 2

Chapter 5 GX Works2 MT91 Parameter Overview

5.1 Intelligent Function Module Software Setup / Switch Settings

In your Project Tree Menu create a new Intelligent Function Module using the QJ71MT91 and assign in to address 0000, which is slot 0.

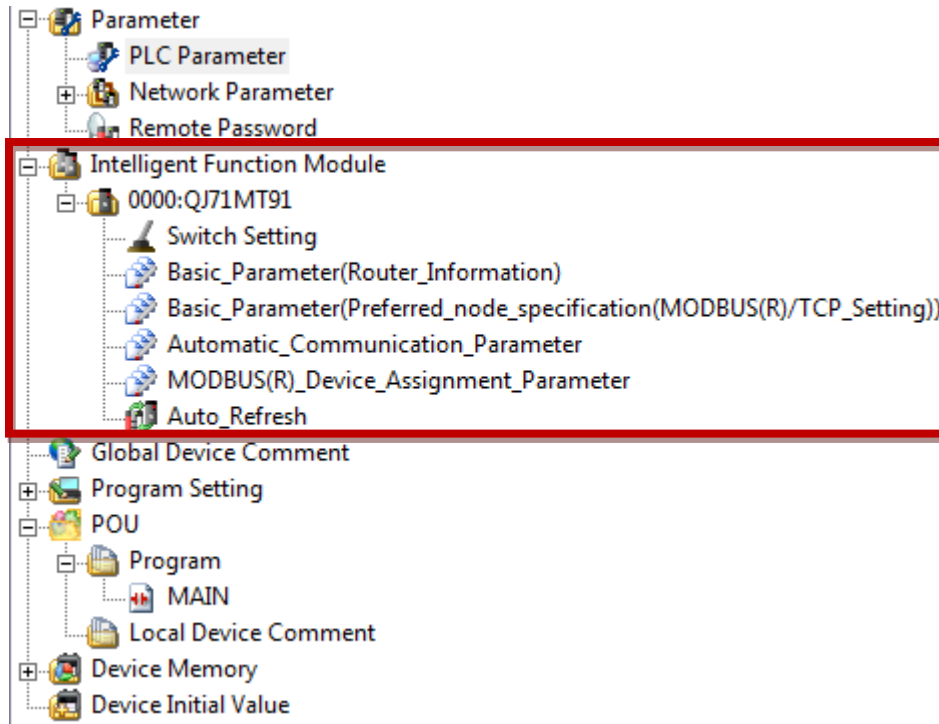


Figure 5.1.1 Project Menu Tree – Intelligent Function Module Creation

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Select "Switch Setting" from Intelligent Function Module → 0000:QJ71MT91.

In this example the default IP Address of the MT91 Module is used. Change as needed. All other parameters are kept at DEFAULT.

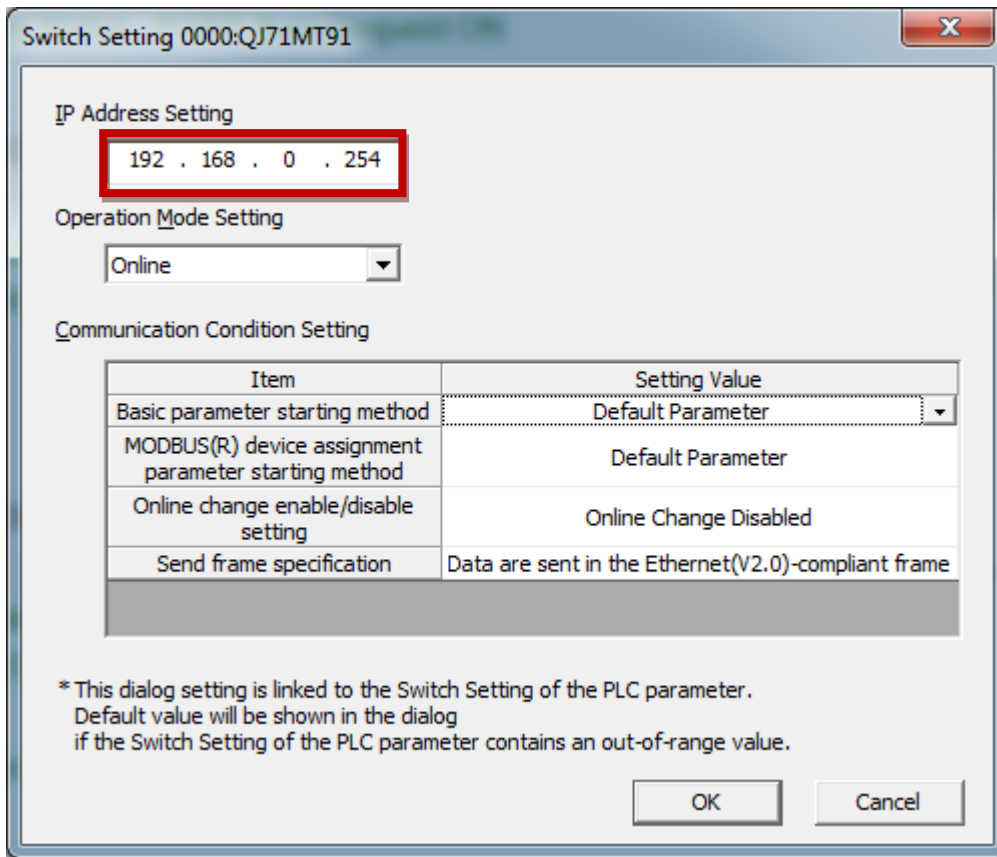


Figure 5.1.2 Switch Setting Detail

5.2 Intelligent Function Module Software Setup / Automatic Communication Parameter

Select "Automatic Communication Parameter" from Intelligent Function Module → 0000:QJ71MT91.

Automatic Communication Parameter	
Automatic Communication Parameter 1	
Target Station IP Address	192.168.0.110
Module ID	255
Repetition Interval Timer Value	0
Response Monitoring Timer Value	0
Type Specification of The Target MODBUS(R) Device	0005h:Write Holding Registers
Read Setting	
The parameter setting concerning reading data from slave.	
Head Buffer Memory Address	0000 h
Target MODBUS(R) Device Head Number	0
Access Points	0
Write Setting	
The parameter setting concerning writing data to slave.	
Head Buffer Memory Address	3000 h
Target MODBUS(R) Device Head Number	2000
Access Points	2

Figure 5.2.1 Automatic Communication Parameter 1 Settings

Choose the following for #1 Settings to Write to Station 192.168.0.110 Modbus Address 402001 and 402002

1. Target Station IP Address = 192.168.0.110
2. Module ID = 255 (Modbus/TCP) DEFAULT
3. Repetition Interval Timer Value = 0 = 0ms (How often the Command is SENT after a RECEIVE)
4. Response Monitoring Timer Value = 0 = 30s (How much time a SEND and RECEIVE is expected, when = to 0 a value of 60 is used (60 X 500ms = 30s))
5. Type Selection of the Target MODBUS Device = 0005h: Write Holding Register (4x type)
6. Head Buffer Memory Address = 3000h - This setting must NOT be duplicated in another Parameter.
7. Target Modbus Device Head Number = 2000 (Modbus Address -1)
8. Access Points = 2 (Consecutive Modbus Addresses)

Automatic Communication Parameter 2	The parameter setting concerning the automatic communication.
Target Station IP Address	192.168.0.110
Module ID	255
Repetition Interval Timer Value	0
Response Monitoring Timer Value	0
Type Specification of The Target MODBUS(R) Device	0500h:Read Holding Registers
Read Setting	The parameter setting concerning reading data from slave.
Head Buffer Memory Address	1000 h
Target MODBUS(R) Device Head Number	2000
Access Points	8
Write Setting	The parameter setting concerning writing data to slave.
Head Buffer Memory Address	0000 h
Target MODBUS(R) Device Head Number	0
Access Points	0

Figure 5.2.2 Automatic Communication Parameter 2 Settings

Choose the following for #2 Settings to Read from Station 192.168.0.110 Modbus Address 402001 - 402008

1. Target Station IP Address = 192.168.0.110
2. Module ID = 255 (Modbus/TCP) DEFAULT
3. Repetition Interval Timer Value = 0 = 0ms (How often the Command is SENT after a RECEIVE)
4. Response Monitoring Timer Value = 0 = 30s (How much time a SEND and RECEIVE is expected, when = to 0 a value of 60 is used (60 X 500ms = 30s))
5. Type Selection of the Target MODBUS Device = 0005h: READ Holding Register (4x type)
6. Head Buffer Memory Address = 1000h – This setting must NOT be duplicated in another Parameter.
7. Target Modbus Device Head Number = 2000 (Modbus Address -1)
8. Access Points = 8 (Consecutive Modbus Addresses)

5.3 Intelligent Function Module Software Setup / Auto Refresh Settings

Select "Auto Refresh" from Intelligent Function Module → 0000:QJ71MT91

Item	
[-] Transfer to PLC	
Auto Communication Function Buffer Input Area	D0 (0,8)
Auto Communication Function Operation Status Storage Area (Parameter 1 to 64)	
User Setting Area (Input)	
[-] Transfer to Intelligent Function Module	
Auto Communication Function Buffer Output Area	D1000 (0,2)
User Setting Area (Output)	

Figure 5.3.1 Automatic Refresh Detail

Define the PLC Data Register starting number (D0), the offset value (keep it at zero) and the number of consecutive Data Registers (8) that will be read from the Slave device(s), Inputs. As the Slave Devices increase the Transfer Word Counts will increase as needed per Slave Device.

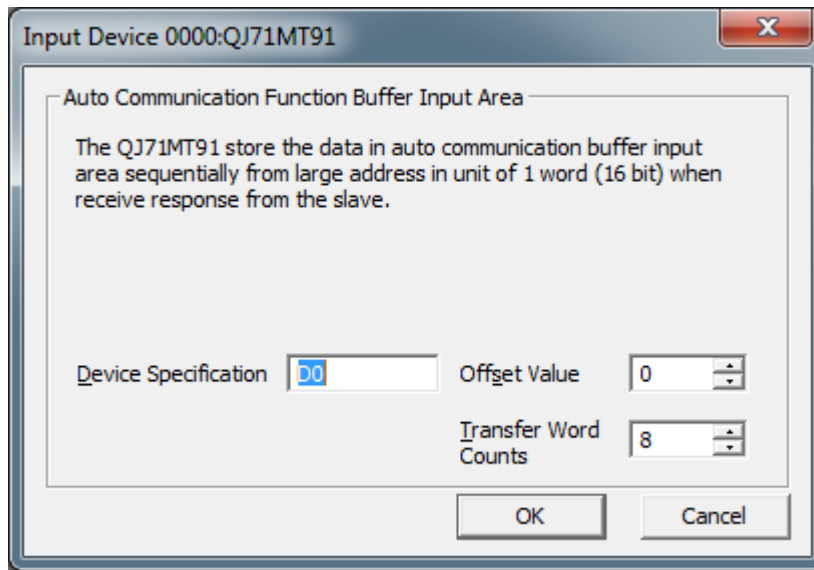


Figure 5.3.2 Data Register Input (Read from Slave) Parameters

5

Define the PLC Data Register starting number (D1000), the offset value (keep it at zero) and the number of consecutive Data Registers (2) that will be written to the Slave device(s), Outputs. As the Slave Devices increase the Transfer Word Counts will increase as needed per Slave Device.

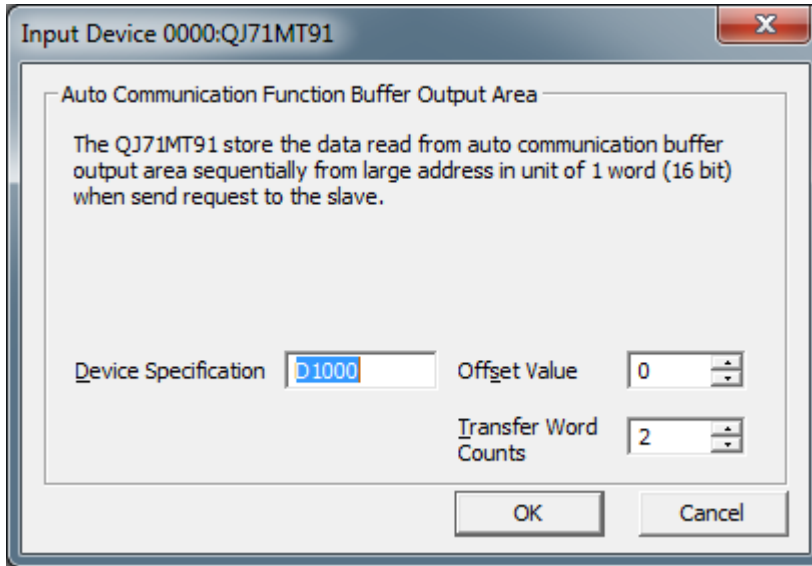


Figure 5.3.3 Data Register Output (Written to Slave) Parameters

These Settings in the Intelligent Function Module Setup are all kept at DEFAULT.

- **Basic Parameter (Router Information)**
- **Basic Parameter (Preferred Node Specification)**
- **Modbus Device Assignment Parameter**

5

5.4 MT91 Master Slave Register Setup

The following table shows the relationship between the Modbus Address (ETH Module), the MT91 BFM location, the PLC Data Register and the Modbus Address in the VFD. **All these items, except Modbus Address (VFD), must be properly aligned in the Intelligent Function Module settings to work properly.**

QJ71MT91 Quick Start Guide Master Slave Register Setup

Send to Slave (Write)

<u>Modbus Address(ETH)</u>	<u>BFM</u>	<u>PLC Data Register</u>	<u>VFD</u>	<u>Modbus Address(VFD)</u>
402001	3000h	← D1000	Command Register	40009
402002	3001h	← D1001	Command Frequency	40014

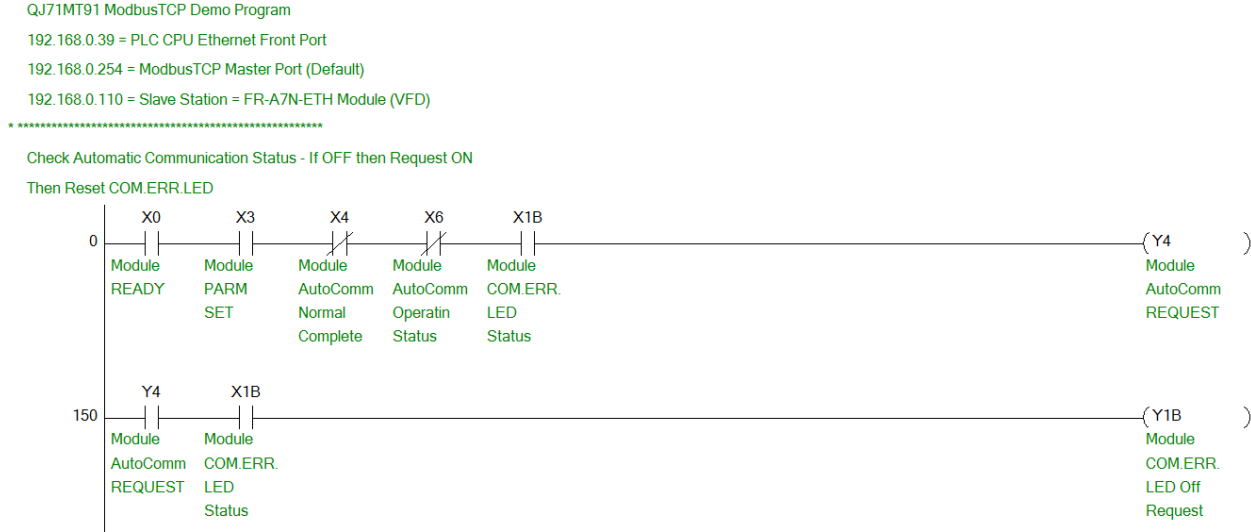
Receive from Slave (Read)

<u>Modbus Address(ETH)</u>	<u>BFM</u>	<u>PLC Data Register</u>	<u>VFD</u>	<u>Modbus Address(VFD)</u>
402001	1000h	→ D0	Commanded Bits	40009
402002	1001h	→ D1	Commanded Freq	40014
402003	1002h	→ D2	Output Frequency	40201
402004	1003h	→ D3	Output Current	40202
402005	1004h	→ D4	Output Voltage	40203
402006	1005h	→ D5	VFD Status Bits	40261
402007	1006h	→ D6	DC Bus Voltage	40208
402008	1007h	→ D7	Cumulative Power	40225

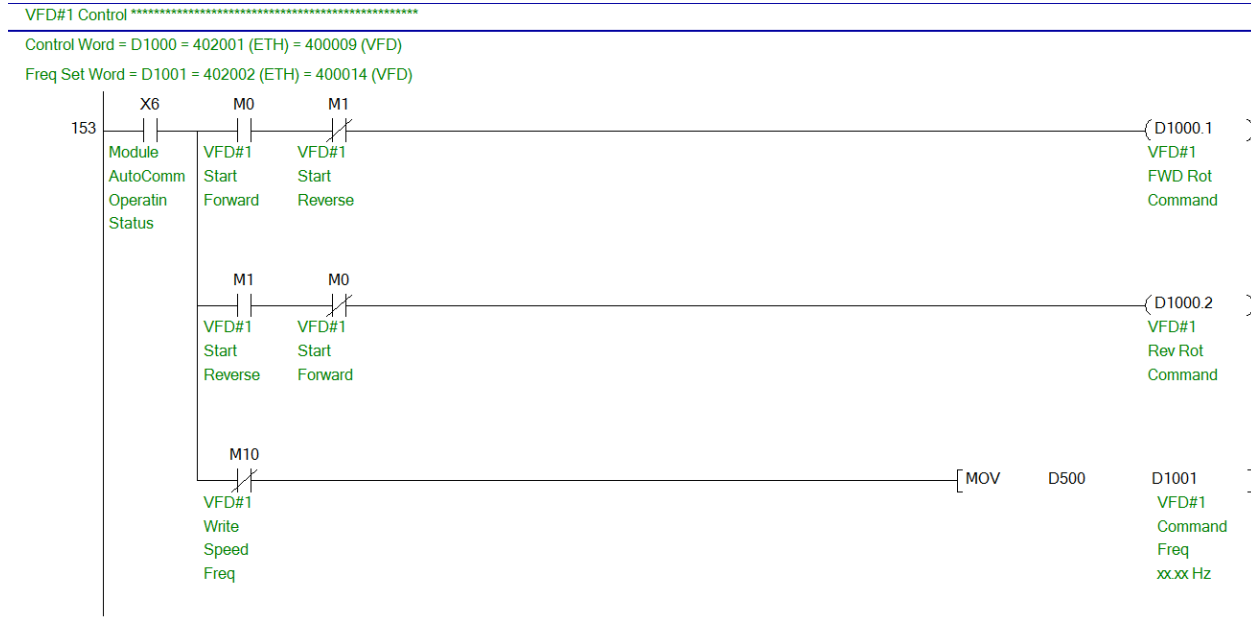
Chapter 6 GX Works2 PLC Program

If Automatic Communication Parameters are setup properly communication with the Slave device(s) will start when the PLC CPU is put into run. If not, the first two lines of code will be needed to turn on the Modbus/TCP Communication between the Master and the slaves.

This code is used to Start Modbus/TCP Communications.

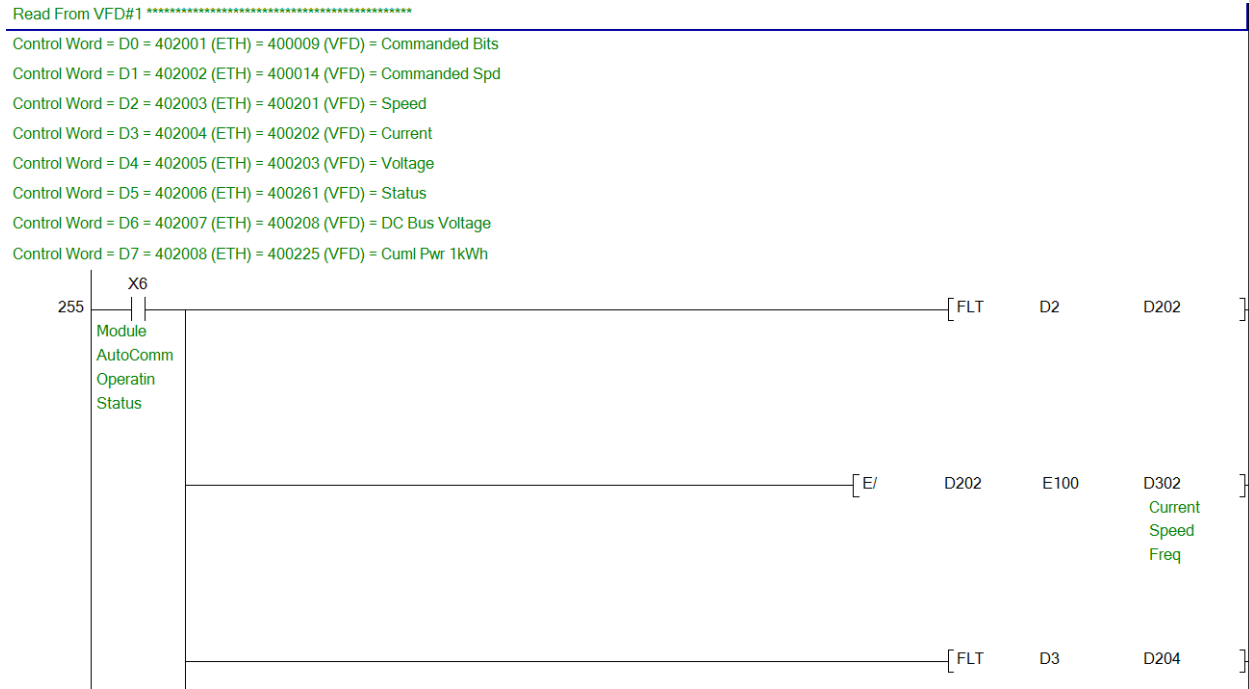


This code writes 2 Data Words to Start the VFD Forward or Reverse and Write Speed/Frequency.



6

This code reads all 8 Data Words from the VFD and converts them to real units (Freq, Current, Volts, etc.).



Revisions

September 2012 – Document Created and Published V1.0